

a motor with a reversible shaft, said motor connected to said controller and engageable with said pump; and a current sensor associated with said motor and connected to said controller;

wherein if said hand sensor detects an object, said controller starts said pump through said motor by rotating said shaft in a first direction, and said controller rotates said reversible shaft in an opposite direction to return said pump to said loading position if said current sensor detects a predetermined level of current.

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